CS 230, Quiz 6

Solutions

You will have 20 minutes to complete this quiz. No books, notes, or other aids are permitted.

You are given these formulas from class:

$$\mathbf{x}_{i} = \mathbf{x} + \mathbf{r}_{i} \qquad \mathbf{v}_{i} = \mathbf{v} + \boldsymbol{\omega} \times \mathbf{r}_{i} \qquad \mathbf{r}_{i} = \mathbf{R}\hat{\mathbf{r}}_{i} \qquad \mathbf{u}^{*}\mathbf{w} = \mathbf{u} \times \mathbf{w} \qquad \mathbf{u}^{*T}\mathbf{w} = \mathbf{w} \times \mathbf{u}$$

$$m = \sum_{i} m_{i} \qquad \mathbf{I} = \sum_{i} m_{i}\mathbf{r}_{i}^{*}\mathbf{r}_{i}^{*T} \qquad \hat{\mathbf{I}} = \sum_{i} m_{i}\hat{\mathbf{r}}_{i}^{*}\hat{\mathbf{r}}_{i}^{*T} \qquad \mathbf{p} = \sum_{i} m_{i}\mathbf{v}_{i} \qquad \mathbf{L} = \sum_{i} \mathbf{r}_{i} \times m_{i}\mathbf{v}_{i}$$

$$\dot{\mathbf{R}} = \boldsymbol{\omega}^{*}\mathbf{R} \qquad \dot{\mathbf{x}} = \mathbf{v} \qquad \dot{\mathbf{p}} = \mathbf{f} \qquad \dot{\mathbf{L}} = \boldsymbol{\tau} \qquad \boldsymbol{\delta} = \text{identity matrix}$$

$$\mathbf{0} = \sum_{i} m_{i}\mathbf{r}_{i} \qquad \mathbf{0} = \sum_{i} m_{i}\hat{\mathbf{r}}_{i} \qquad \mathbf{L} = \mathbf{I}\boldsymbol{\omega} \qquad \mathbf{p} = m\mathbf{v} \qquad \mathbf{u}_{i}^{*}\mathbf{u}_{i}^{*T} = \boldsymbol{\delta}(\mathbf{u}^{T}\mathbf{u}) - \mathbf{u}\mathbf{u}^{T}$$

Problem 1 (1 points)

The total kinetic energy of a rigid body is just the total energy of its parts,

$$E = \sum_{i} \frac{1}{2} m_i \mathbf{v}_i \cdot \mathbf{v}_i.$$

Derive a formula for E that depends only on the state of the rigid body $(\mathbf{x}, \mathbf{R}, \mathbf{v}, \boldsymbol{\omega}, m, \mathbf{I}, \mathbf{p}, \mathbf{L})$.

$$E = \sum_{i} \frac{1}{2} m_{i} \mathbf{v}_{i} \cdot \mathbf{v}_{i}$$

$$= \sum_{i} \frac{1}{2} m_{i} (\mathbf{v} + \boldsymbol{\omega} \times \mathbf{r}_{i}) \cdot (\mathbf{v} + \boldsymbol{\omega} \times \mathbf{r}_{i})$$

$$= \sum_{i} \frac{1}{2} m_{i} \mathbf{v} \cdot \mathbf{v} + \sum_{i} m_{i} \mathbf{v} \cdot (\boldsymbol{\omega} \times \mathbf{r}_{i}) + \sum_{i} \frac{1}{2} m_{i} (\boldsymbol{\omega} \times \mathbf{r}_{i}) \cdot (\boldsymbol{\omega} \times \mathbf{r}_{i})$$

$$= \frac{1}{2} \left(\sum_{i} m_{i} \right) \mathbf{v} \cdot \mathbf{v} + \mathbf{v} \cdot \left(\boldsymbol{\omega} \times \sum_{i} m_{i} \mathbf{r}_{i} \right) + \frac{1}{2} \sum_{i} m_{i} (\mathbf{r}_{i}^{*T} \boldsymbol{\omega})^{T} (\mathbf{r}_{i}^{*T} \boldsymbol{\omega})$$

$$= \frac{1}{2} m \mathbf{v} \cdot \mathbf{v} + \mathbf{v} \cdot (\boldsymbol{\omega} \times \mathbf{0}) + \frac{1}{2} \boldsymbol{\omega}^{T} \left(\sum_{i} m_{i} \mathbf{r}_{i}^{*} \mathbf{r}_{i}^{*T} \right) \boldsymbol{\omega}$$

$$= \frac{1}{2} m \mathbf{v} \cdot \mathbf{v} + \frac{1}{2} \boldsymbol{\omega}^{T} \mathbf{I} \boldsymbol{\omega}$$